

Fig. 2

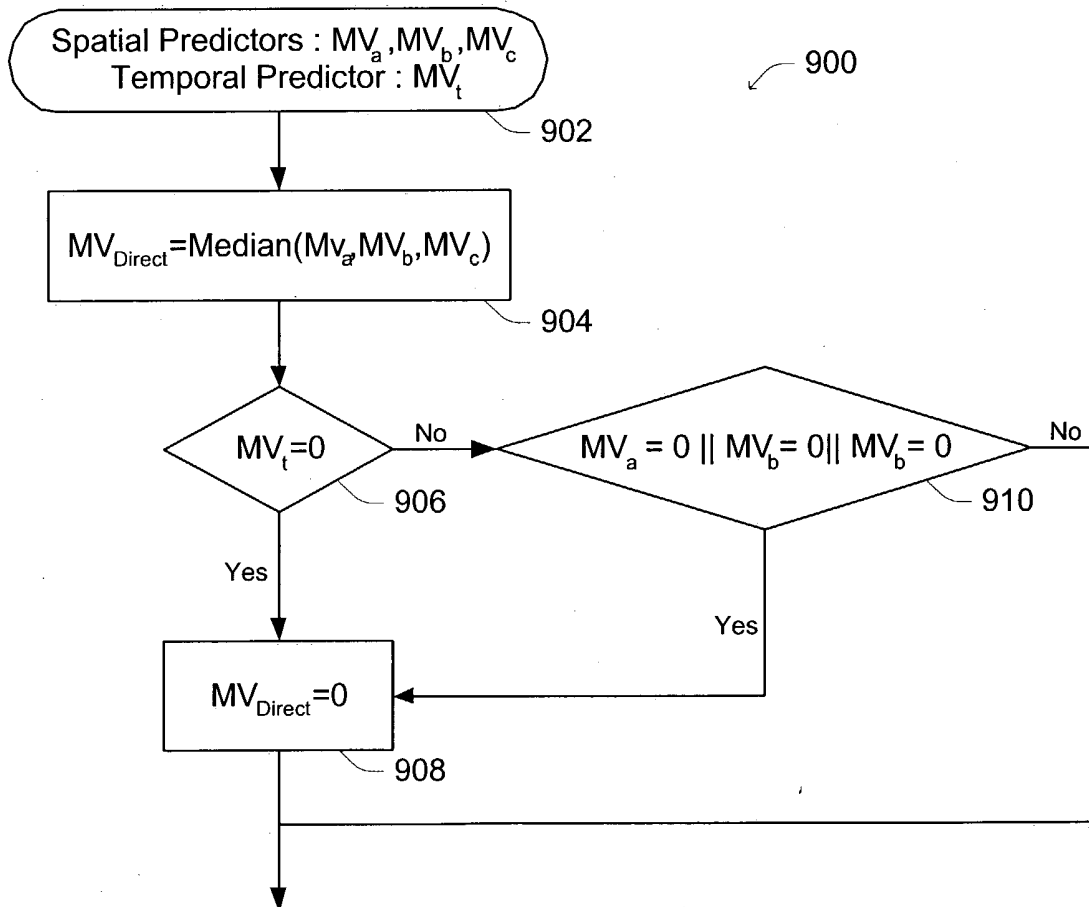


Fig. 9

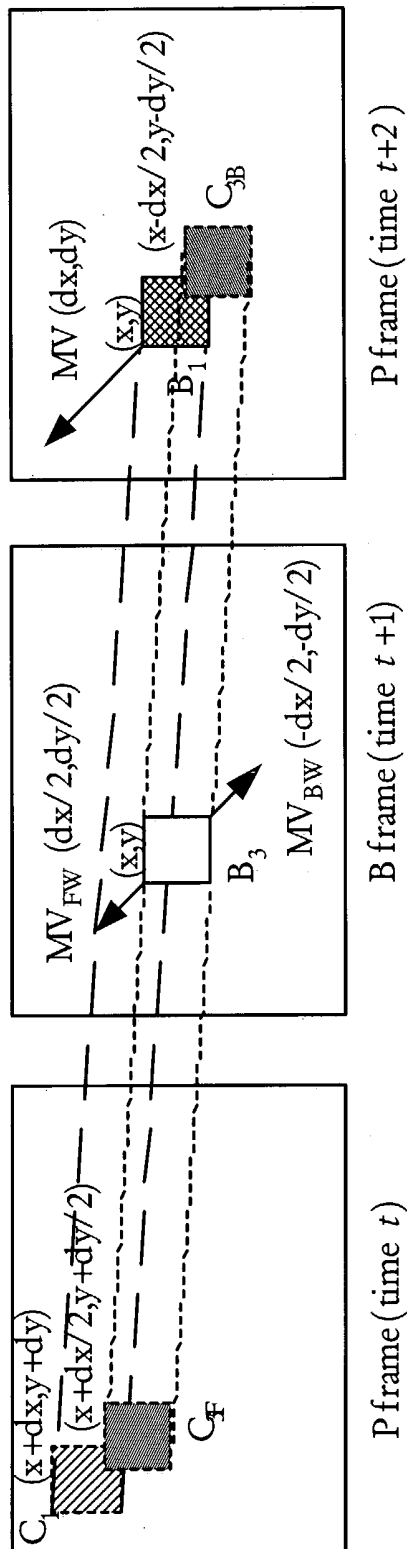


Fig. 3

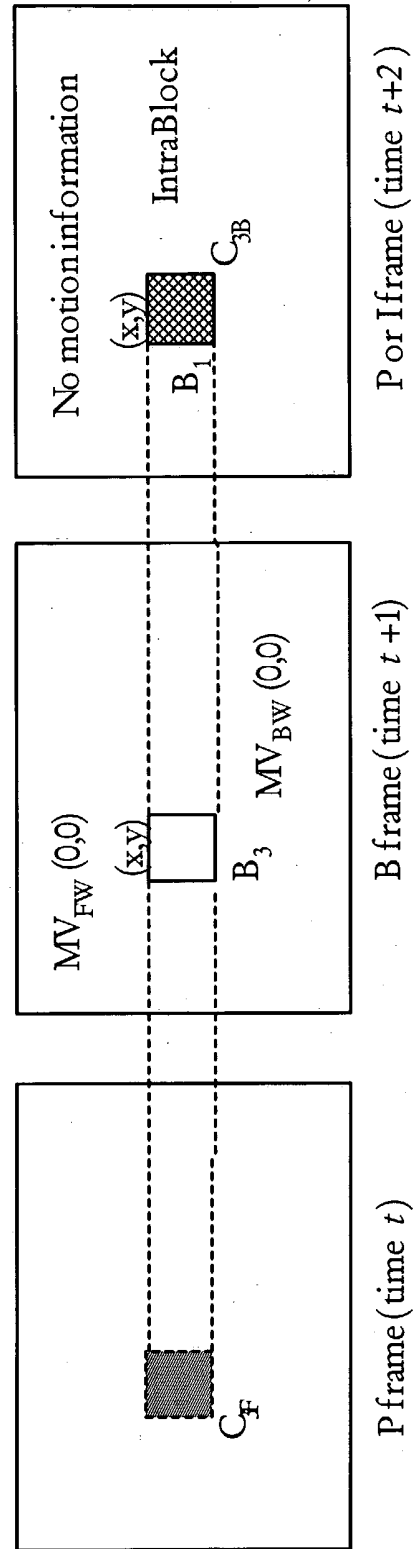


Fig. 4

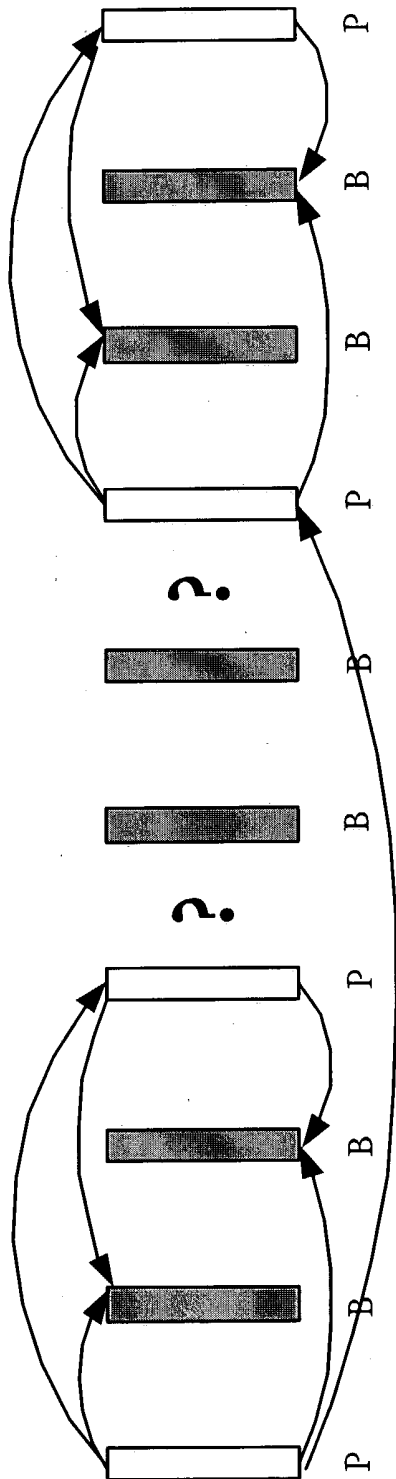


Fig. 5

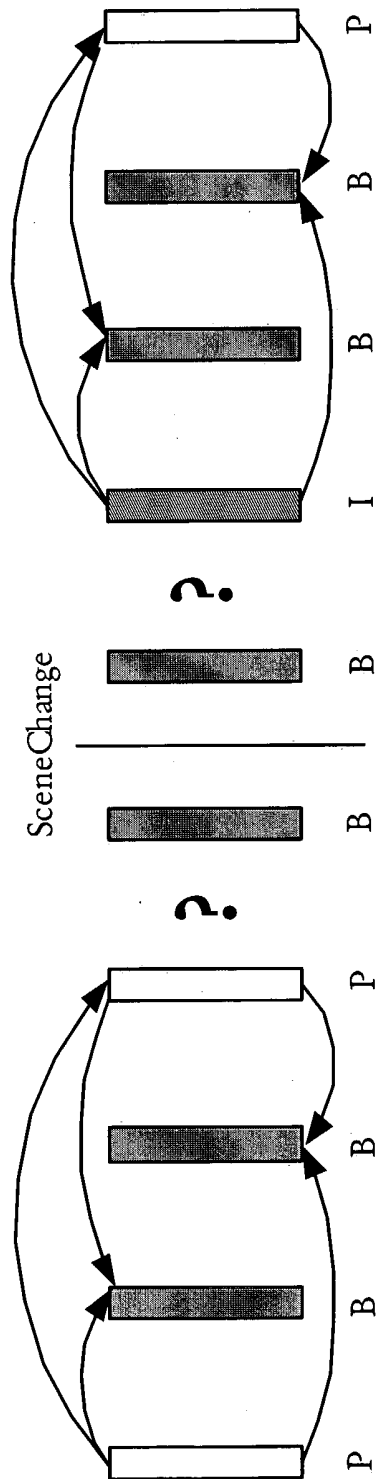


Fig. 6

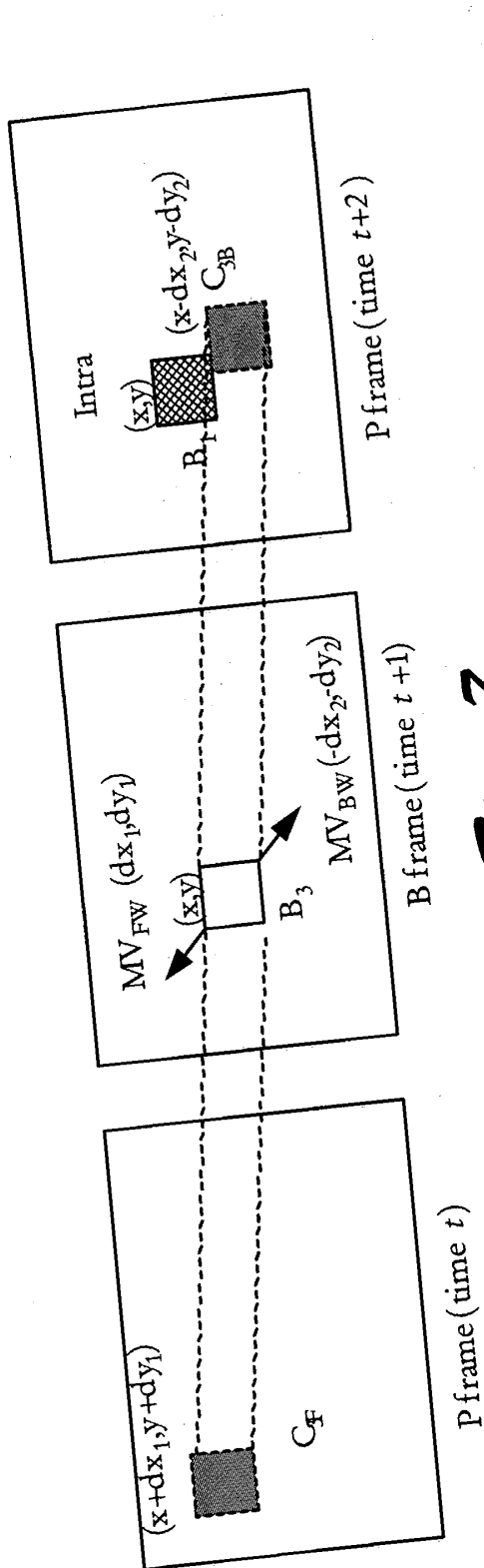


Fig. 7

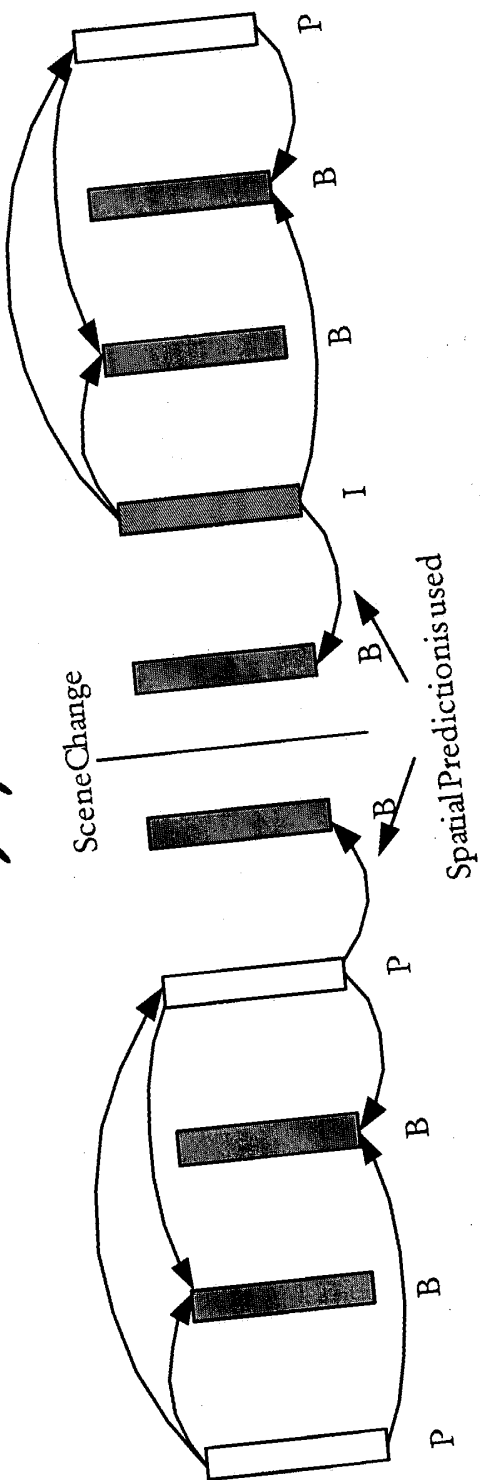
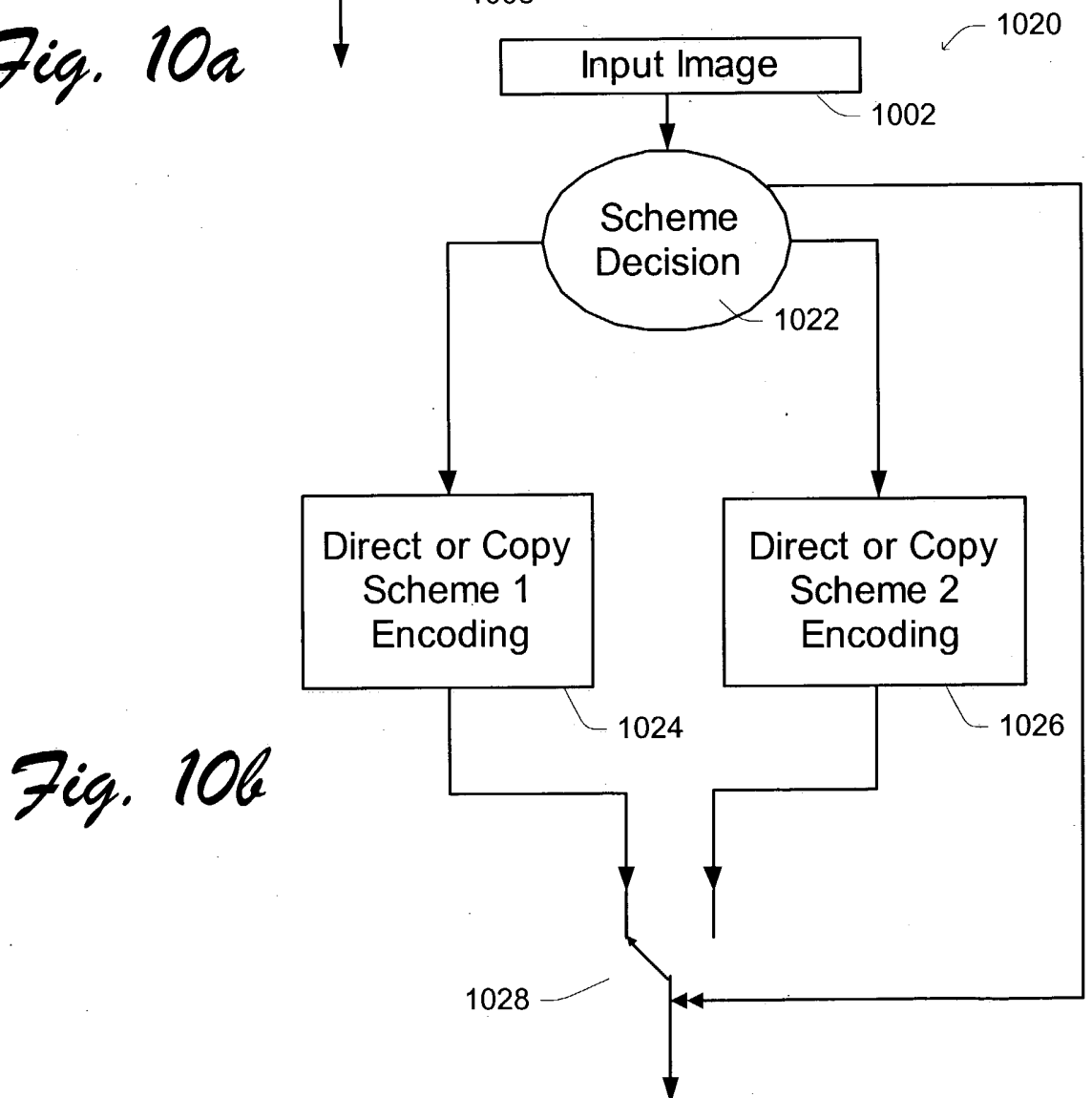
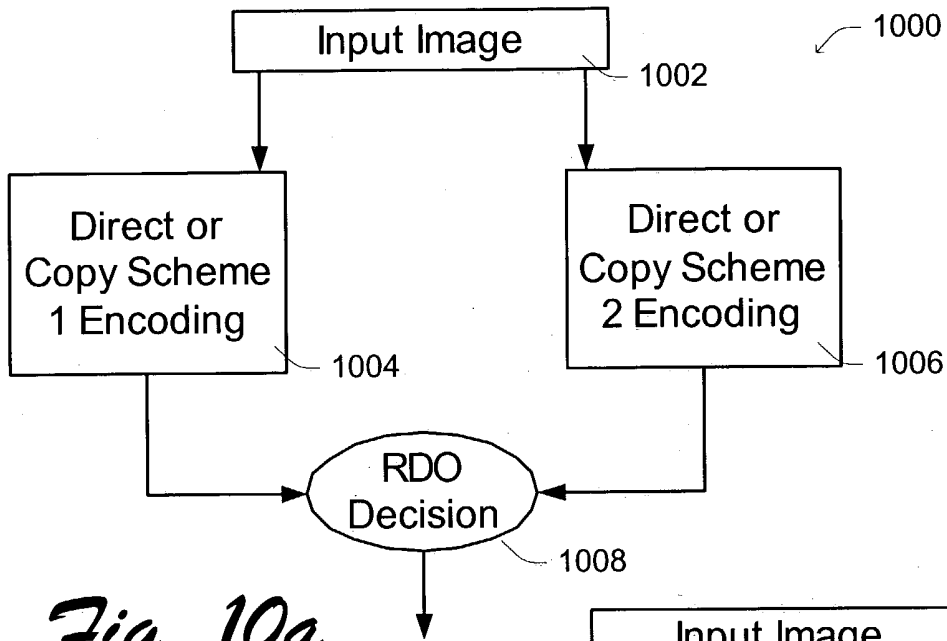


Fig. 8



slice_header() {	Category	Descriptor
parameter_set_id	4	e(v)
first_mb_in_slice	4	e(v)
if (coding_type() == Inter coding_type() == Bipred) {		
num_ref_pic_active_fwd_minus1	4	e(v)
if(coding_type() == Bipred)		
num_ref_pic_active_bwd_minus1	4	e(v)
if(coding_type() == Inter)		
copy_mv_spatial	4	u(1) or e(v)
if(coding_type() == Bipred) {		
direct_mv_spatial	4	u(1) or e(v)
if(direct_mv_spatial) {		
direct_mv_scale_fwd	4	e(v)
direct_mv_scale_bwd	4	e(v)
direct_mv_scale_divisor	4	e(v)
}		
explicit_B_prediction_block_weight_indication		e(v)
if (explicit_B_prediction_block_weight_indication > 1)		
adaptive_B_prediction_coeff_table()		
}		
}		
rps_layer()		
slice_qp_minus26 /* relative to 26 */	4	e(v)
if(coding_type() == SP coding_type() == SI) {		
if (coding_type() == SP)		
sp_for_switch_flag	4	u(1)
slice_qp_s_minus26 /* relative to 26 */	4	e(v)
}		
if(entropy_coding_mode == 1)		
num_mbs_in_slice	4	e(v)
}		

Fig. 11

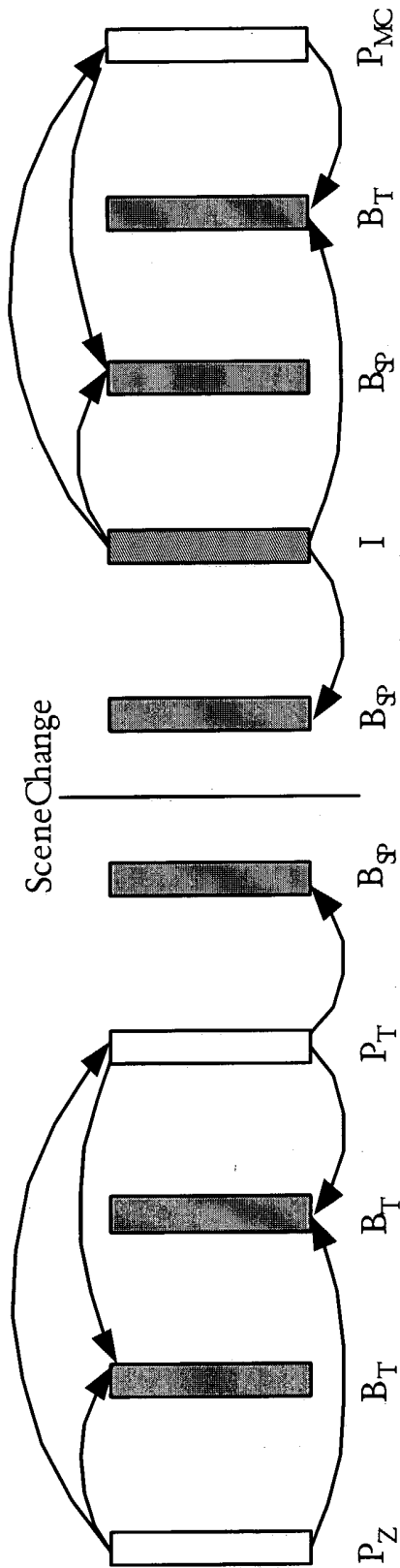


Fig. 12

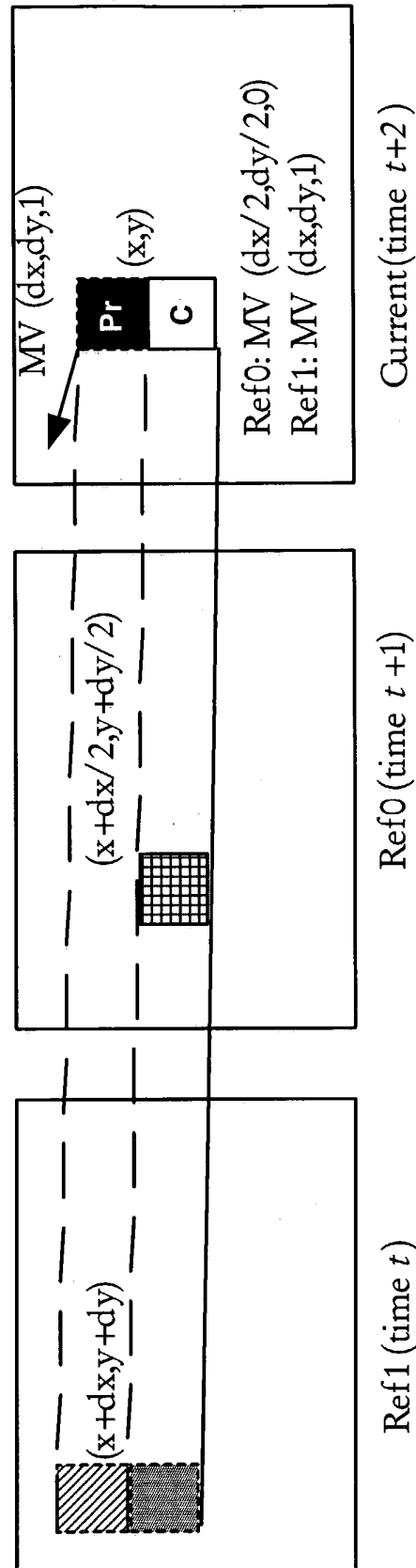
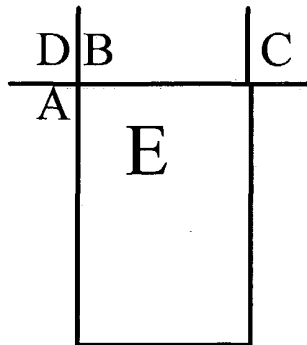


Fig. 18

Modes for 8x8 blocks in B pictures/slices

Code number	8x8 partition mode	num_subblock_block8x8()	block_prediction_mode()
0	Direct8x8	1	Direct
1	8x8	1	Fwd
2	8x8	1	Bwd
3	8x8	1	Bipred
4	8x4	2	Fwd
5	4x8	2	Fwd
6	8x4	2	Bwd
7	4x8	2	Bwd
Removed	8x4	2	Bipred
Removed	4x8	2	Bipred
8	4x4	4	Fwd
9	4x4	4	Bwd
Removed	4x4	4	Bipred
10	Intra8x8	1	Intra

Fig. 13*Fig. 14*

P-Picture Motion Vector Prediction (Non-Skip, non-8x16, non-16x8 MBs)

Availability of Neighbor MV				MV Prediction v_E derivation for E	Defined
A	B	C	D		
0	0	0	0	1 st rule: $v_A=0$; $v_D=0$; $r_A \neq r_E$; $r_D \neq r_E$; 2 nd rule: $v_E=v_A=0$;	✓
0	0	0	1	3 rd rule: $v_C=v_D$; $r_C=r_D$; v_E Not defined since v_A not defined.	×
0	0	1	0	1 st rule: $v_A=0$; $v_D=0$; $r_A \neq r_E$; $r_D \neq r_E$; v_E Not defined since v_B not defined.	×
0	0	1	1	v_E Not defined since v_A and v_B not defined.	×
0	1	0	0	1 st rule: $v_A=0$; $v_D=0$; $r_A \neq r_E$; $r_D \neq r_E$; 3 rd rule: $v_C=v_D=0$; $r_C=r_D \neq r_E$; 4 th rule: if B uses same reference picture as E, then $v_E=v_B$; else $v_E=\text{median}(v_A, v_B, v_C)=\text{median}(0, v_B, 0)=0$;	✓
0	1	0	1	3 rd rule: $v_C=v_D$; $r_C=r_D$ v_E Not defined since v_A not defined.	✓
0	1	1	0	1 st rule: $v_A=0$; $v_D=0$; $r_A \neq r_E$; $r_D \neq r_E$; 4 th rule: if one and only one of B, C uses same reference picture as E, then $v_E=v_B$ or v_C (whichever uses same ref pic); else $v_E=\text{median}(v_A, v_B, v_C)=\text{median}(0, v_B, v_C)$; [even if v_B and v_C use different reference pictures than v_E]	✓
0	1	1	1	v_E Not defined since v_A not defined.	×
1	0	0	0	2 nd rule: $v_E=v_A$;	✓
1	0	0	1	3 rd rule: $v_C=v_D$; $r_C=r_D$ v_E Not defined since v_B not defined.	×
1	0	1	0	v_E Not defined since v_B not defined.	×
1	0	1	1	v_E Not defined since v_B not defined.	×
1	1	0	0	3 rd rule: $v_C=v_D$; $r_C=r_D$ v_E Not defined since v_D not defined.	×
1	1	0	1	3 rd rule: $v_C=v_D$; $r_C=r_D$ 4 th rule: if one and only one of A, B, C(D) uses same reference picture as E, then $v_E=v_A$ or v_B or v_C (whichever uses same ref pic); else $v_E=\text{median}(v_A, v_B, v_C)$; [even if one or two of v_A , v_B and v_C use different reference pictures than v_E]	✓
1	1	1	0	4 th rule: if one and only one of A, B, C uses same reference picture as E, then $v_E=v_A$ or v_B or v_C (whichever uses same ref pic); else $v_E=\text{median}(v_A, v_B, v_C)$ [even if one or two of v_A , v_B and v_C use different reference pictures than v_E]	✓
1	1	1	1	4 th rule: if one and only one of A, B, C uses same reference picture as E then $v_E=v_A$ or v_B or v_C (whichever uses same ref pic); else $v_E=\text{median}(v_A, v_B, v_C)$; [even if one or two of v_A , v_B and v_C use different reference pictures than v_E]	✓

Fig. 15

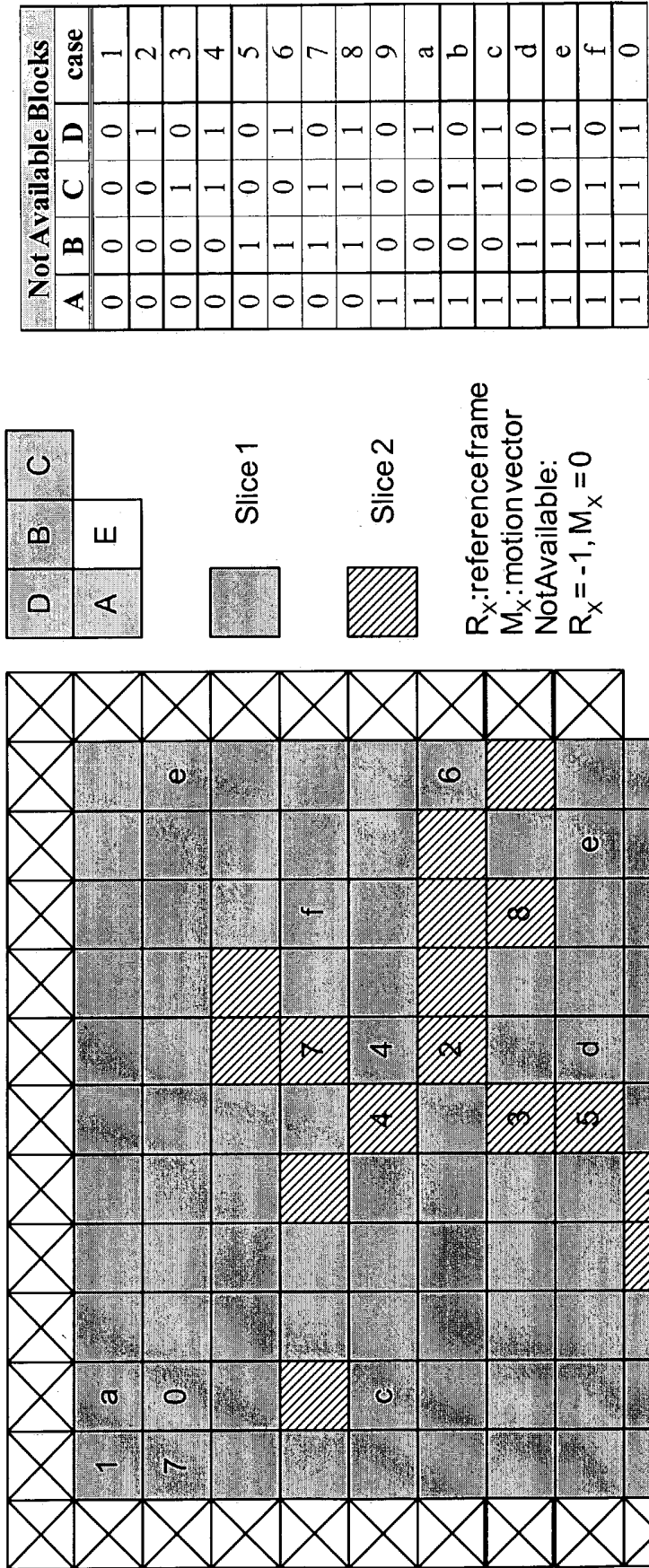
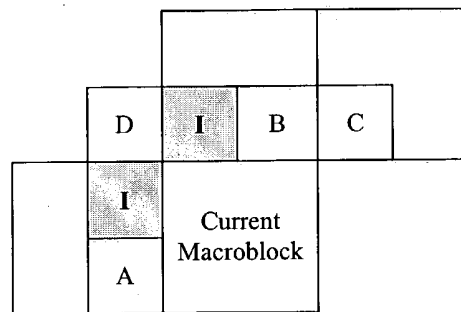
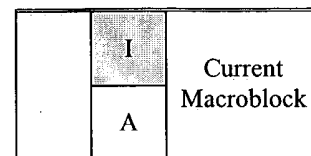


Fig. 16

- JVTRules:
- R0: Median rule is applied for Motion vector calculation: $M_E = \text{Median}(M_A, M_B, M_C)$
 - R1: A, D outside of picture $\Rightarrow R_A = R_D = -1, M_A = M_D = 0$
 - R2: B, C, D outside of picture $\Rightarrow M_E = M_A$
 - R3: C not available (outside of picture, not yet coded etc) C is replaced by D
 - R4: if X is intra, then $R_x = -1$ (no definition on M_x - code sets $R_x = -1, M_x = 0$)
 - R5: if $X(X \in \{A, B, C\})$ and only X has $R_x == R_E$ then $M_E = M_x$

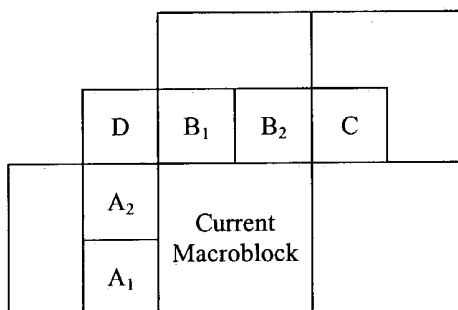


(a)

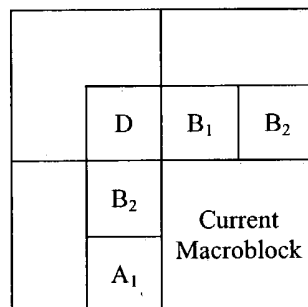


(c)

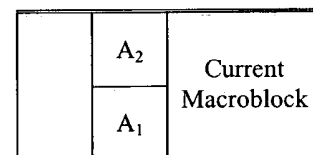
Fig. 17



(a)



(b)



(c)

Fig. 19

Relationship between previous λ and current one.

QP	$\lambda_{I,P}^{Prev} = 5 \times \frac{QP+5}{34-QP} \times \exp \frac{QP}{10}$	$\lambda_{I,P}^{Curr} = 0.85 \times 2^{\frac{QP}{3}}$	$\frac{\lambda_{I,P}^{Curr} - \lambda_{I,P}^{Prev}}{\lambda_{I,P}^{Curr}}$
16	28.89	34.27	18.61%
17	35.42	43.18	21.90%
18	43.48	54.40	25.11%
19	53.49	68.54	28.14%
20	65.97	86.35	30.89%
21	81.66	108.80	33.23%
22	101.53	137.08	35.01%
23	126.94	172.71	36.05%
24	159.84	217.60	36.14%
25	203.04	274.16	35.03%
26	260.86	345.42	32.42%
27	340.11	435.20	27.96%
28	452.23	548.32	21.25%

Fig. 20

Performance different of Proposed Schemes/Draft text and proposed RDO vs current software (JM3.3)

Scheme	ref	Entropy	Sequence	Foreman	Container	News	Paris	Silence	Mobile	Tempete
MVP	1	UVLC	PSNR gain	0.190	0.076	-0.027	0.270	0.099	0.220	-0.135
			Bitrate diff	3.43%	1.39%	-0.47%	5.04%	2.06%	4.43%	-3.53%
	5	UVLC	PSNR gain	0.221	0.037	0.004	0.318	0.129	0.256	-0.156
			Bitrate diff	3.98%	0.59%	0.07%	5.96%	2.66%	4.81%	-4.00%
MVP	1	CABAC	PSNR gain	0.081	0.022	-0.026	0.194	0.062	0.116	-0.167
			Bitrate diff	1.52%	0.40%	-0.45%	3.65%	1.25%	2.32%	-4.32%
	5	CABAC	PSNR gain	0.101	0.011	0.009	0.233	0.100	0.150	-0.183
			Bitrate diff	1.89%	0.21%	0.14%	4.37%	2.04%	2.93%	-4.70%
T+MVP	1	UVLC	PSNR gain	0.020	-0.006	0.010	0.001	0.004	0.001	0.004
			Bitrate diff	0.37%	-0.13%	0.18%	0.03%	0.09%	0.02%	0.11%
	5	UVLC	PSNR gain	0.063	-0.009	0.025	0.016	0.033	0.015	-0.028
			Bitrate diff	1.14%	-0.18%	0.43%	0.30%	0.70%	0.31%	-0.70%
T+MVP	1	CABAC	PSNR gain	0.011	-0.004	0.006	0.003	-0.001	0.002	0.006
			Bitrate diff	0.20%	-0.08%	0.09%	0.06%	-0.01%	0.05%	0.16%
	5	CABAC	PSNR gain	0.025	-0.015	0.018	0.014	0.023	0.016	-0.024
			Bitrate diff	0.47%	-0.27%	0.31%	0.27%	0.48%	0.34%	-0.62%
T+MVP RDO	1	UVLC	PSNR gain	0.069	0.439	0.106	0.370	0.144	0.629	0.226
			Bitrate diff	1.26%	8.27%	1.87%	6.81%	2.96%	12.15%	5.48%
	5	UVLC	PSNR gain	0.111	0.406	0.119	0.393	0.163	0.676	0.196
			Bitrate diff	2.00%	7.53%	2.07%	7.29%	3.33%	12.19%	4.66%
T+MVP RDO	1	CABAC	PSNR gain	0.040	0.390	0.107	0.288	0.113	0.529	0.196
			Bitrate diff	0.73%	7.26%	1.80%	5.36%	2.29%	10.32%	4.79%
	5	CABAC	PSNR gain	0.056	0.375	0.120	0.304	0.127	0.550	0.159
			Bitrate diff	1.05%	6.91%	1.97%	5.64%	2.59%	10.40%	3.82%
Draft	5	UVLC	PSNR gain	-0.012	-0.047	-0.018	-0.003	0.000	-0.080	-0.120
			Bitrate diff	-0.22%	-0.90%	-0.32%	0.07%	0.00%	-1.72%	-3.03%
	5	CABAC	PSNR gain	-0.003	-0.042	-0.016	0.000	0.004	-0.067	-0.112
			Bitrate diff	-0.05%	-0.78%	-0.26%	-0.01%	0.08%	-1.43%	-2.85%

Fig. 21

Comparison of encoding performance for different values of λ .

A	Q _P _B	Sequence	Foreman	Container	News	Paris	Silence	Mobile	Tempete
500	Q _P _P	PSNR	0.128	-0.015	0.084	0.117	0.039	0.280	0.156
		Bitrate	3.43%	-0.33%	2.01%	2.85%	1.06%	6.35%	3.89%
	Q _P _P +1	PSNR	0.102	-0.111	0.057	0.048	0.005	0.133	0.094
		Bitrate	2.58%	-2.78%	1.39%	1.19%	0.16%	3.04%	2.35%
700	Q _P _P	PSNR	0.070	0.034	0.061	0.079	0.009	0.176	0.086
		Bitrate	1.87%	0.79%	1.43%	1.97%	0.19%	4.08%	2.19%
	Q _P _P +1	PSNR	0.060	-0.012	0.043	0.046	0.002	0.090	0.057
		Bitrate	1.60%	-0.35%	0.97%	1.16%	0.03%	2.19%	1.52%

Fig. 22

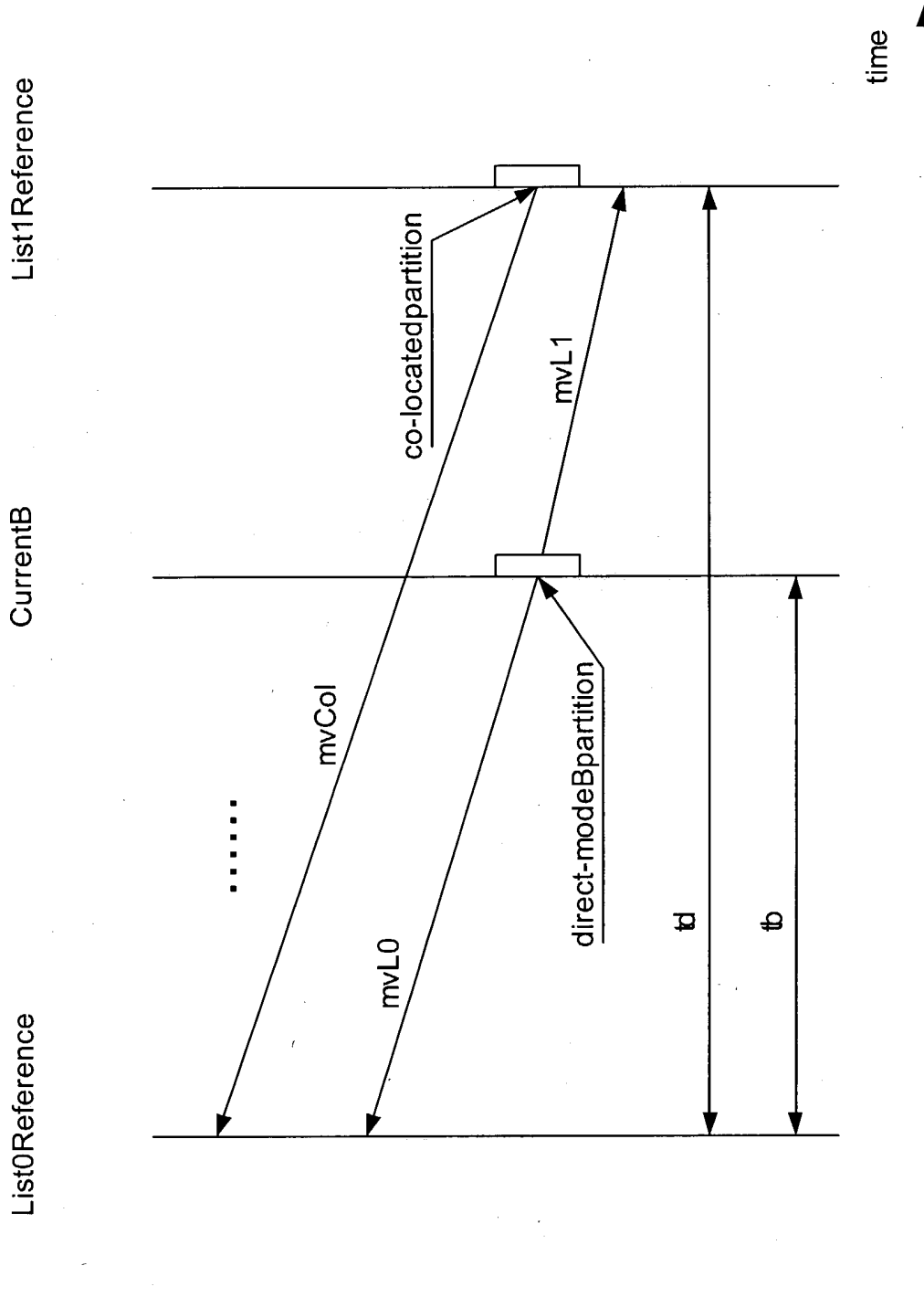


Fig. 23